

**ECE 301 (Section 001) Homework 8**  
**Spring 2023, Dr. Chau-Wai Wong**  
**TA in Charge: Mushfiqur Rahman**

**Problem 1** (Projection and PCA) You are given a data matrix

$$\mathbf{X} = \begin{bmatrix} -0.92 & 1.09 & -1.35 & 2.06 & -0.60 & -0.28 \\ -0.08 & 1.15 & -1.67 & 1.08 & -1.14 & 0.66 \end{bmatrix}.$$

and its principal component  $\mathbf{u} = [0.7474, 0.6644]^T$ .

- a) Plot the data points using circles and the principal component using a line segment with one end at  $[0, 0]^T$  on a 2D plane using Matlab.
- b) Calculate the projection  $c_i$  for each data point  $\mathbf{x}_i$  to  $\mathbf{u}$ . Note that  $c_i$  can be negative.
- c) Calculate the sample variance of  $\{c_i\}_{i=1}^n$ , namely,

$$\widehat{\text{Var}}(\{c_i\}) = \frac{1}{n-1} \sum_{i=1}^n (c_i - \bar{c})^2,$$

where  $\bar{c} \stackrel{\text{def}}{=} \frac{1}{n} \sum_{i=1}^n c_i$  is the sample mean.

- d) Repeat b) and c) using another unit vector  $\mathbf{u}_a = [0.8, 0.6]^T$ . Is the newer sample variance smaller than that in b)? Can you explain why?

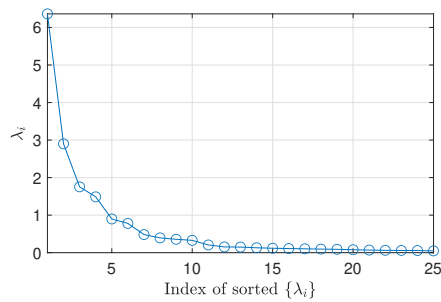
**Problem 2** (Orthogonal and Unitary Matrices)

You have learned in class that a real-valued *orthogonal matrix*  $\mathbf{P}$  has the property that  $\mathbf{P}^T \mathbf{P} = \mathbf{P} \mathbf{P}^T = \mathbf{I}$ . In signal processing, oftentimes signals are represented in complex values. We can define for a complex-valued square matrix a similar concept called the *unitary matrix*. A unitary matrix  $\mathbf{Q}$  satisfies the property that  $\mathbf{Q}^H \mathbf{Q} = \mathbf{Q} \mathbf{Q}^H = \mathbf{I}$ , where “ $H$ ” is the Hermitian operator that is a combination of both the transpose, “ $T$ ,” and the complex conjugate, “ $*$ .”

- a) The discrete Fourier transform (DFT) matrix for a signal of length 3 is defined as  $\mathbf{Q}_3 = [q_{kn}]_{k,n \in \{0,1,2\}}$ , where  $q_{kn} = \frac{1}{\sqrt{3}} \exp(-j \frac{2\pi}{3} kn)$ . Explicitly write out this 3-by-3 matrix. Simplify each entry but do not evaluate numerically the complex exponentials.
- b) Verify that  $\mathbf{Q}_3$  is a unitary matrix.
- c) Compute the forward discrete Fourier transform for signal  $\mathbf{x} = [1.01, 0.99, 0.97]^T$  to obtain a transformed signal  $\mathbf{z} = \mathbf{Q}_3 \mathbf{x}$ , where  $\mathbf{z} = [z_0, z_1, z_2]^T$ . How large are the norms for  $z_0$ ,  $z_1$ , and  $z_2$ ?
- d) Now, zero out  $z_2$  to obtain a new vector  $\mathbf{z}_{\text{compressed}}$ . Compute the inverse transform using  $\hat{\mathbf{x}} = \mathbf{Q}_3^H \mathbf{z}_{\text{compressed}}$ . Is  $\hat{\mathbf{x}}$  similar to  $\mathbf{x}$ ? Can you guess why?

**Problem 3** (PCA on Downsampled Yale Face Database) In this problem, we will explore PCA as a visualization tool for Yale Face Database. Download the .m files and the database. Extract the face image files into a folder named `yalefaces` and put the .m files at the same level of the folder. Call this folder “`problem_pca_face/`”. Open Matlab, change your “Current Folder” to “`problem_pca_face/`”, and open `main_pca_visualization.m`.

- a) Run the code corresponding to this part only, describe the data structure of variable `img_buffer`. Set `preview_img_flag` to 1, re-run the code to visually inspect the whole database.
- b) Complete Matlab function `[V, Lambda_mat] = PcaViaKlt(data)` by implementing PCA using eigendecomposition on a sample covariance matrix of the face data. The detailed information about the input and outputs are given in the comments of the incomplete function. You may use built-in function `eig` for eigendecomposition. If your implementation is correct, after running the code of b), you will obtain a plot similar to the following.



- c) Run the code of c) to visualize a few dominating eigenvectors. Comment on whether they reflect some characteristics of the faces you saw in a).
- d) The code of d) projects each face image (coming from one of the four selected classes) onto a 2D space. Comment on PCA’s data visualization performance in this specific example.

**Problem 4** (Deep Learning with Matlab) In recent updates, Matlab has put together well-guided tutorials for deep learning. This is one set of tutorials on “Deep Learning with Images”. Complete the following tutorials by running the example code:

“Classify Webcam Images Using Deep Learning.”

Write a concise report consisting of key source code, images, and your explanations.

For more tutorials, see the left menu on this page: <https://www.mathworks.com/help/deeplearning/getting-started-with-deep-learning-toolbox.html>

These tutorials may give you ideas about your projects in other courses.

**Group Study (1', bonus)** Zoom: Take a screenshot of the whole team with everyone's webcam capturing his/her face. One of you will share the screen showing the specific homework assignment sheet that you are working on. In-Person: Take a selfie with all group members' faces in the photo. Capture the homework assignment sheet in the photo.

Include the screenshot/selfie in your own homework submission as the last "problem." Your screenshot/selfie gets you 1 bonus point; your group members need to do it separately to earn their bonus points.