

Normal Equations & Geo Interpretations

1. Simple linear regression model

Data (x_i, Y_i) , $i=1, \dots, n$ random $E[e_i] = 0$

model : $Y_i = \beta_0 + \beta_1 x_i + e_i$

\uparrow \uparrow \uparrow
intercept indep. var./
dependent predictor
var./observation

noise: measurement noise,
biological variation

$\theta = [\beta_0, \beta_1]^T$ is the param vector/weights

$E[Y_i] = \beta_0 + \beta_1 x_i = \text{lin. comb. of unknowns } \beta's,$
w/ known coeff $(1, x_i)$.

$$\tilde{Y} = \begin{pmatrix} Y_1 \\ \vdots \\ Y_n \end{pmatrix}_{n \times 1}, \quad X = \begin{pmatrix} 1 & | & x_1 \\ \vdots & | & \vdots \\ 1 & | & x_n \end{pmatrix}_{n \times 2}, \quad \beta = \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}_{2 \times 1}, \quad \tilde{\epsilon} = \begin{pmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{pmatrix}_{n \times 1}$$

$\underbrace{\mathbb{1}}_{\tilde{Y}}$ $\underbrace{X}_{\tilde{X}}$

$$\tilde{Y} = X \tilde{\beta} + \tilde{\epsilon}$$

↑
data matrix

"Matrix-vector form"

$$E[\tilde{Y}] = X \tilde{\beta} = [\mathbb{1} \quad \tilde{X}] \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix} = \beta_0 \mathbb{1} + \beta_1 \tilde{X}$$

2. (Multiple) Linear regression model

$$y_i = \sum_{j=1}^p x_{ij} \beta_j + e_i, \quad i=1, \dots, n.$$

$$\begin{matrix} Y \\ \downarrow \end{matrix}_{n \times 1} = X_{n \times p} \beta_{p \times 1} + \underbrace{\varepsilon_{n \times 1}}_{\text{vector of rand. elements.}}$$

Common Assumptions:

$$\mathbb{E}[\varepsilon] = 0$$

$$\text{Var}(e_i) = \sigma^2, \quad i=1, \dots, n.$$

$$\mathbb{E}[e_i^2] = \text{Var}(e_i) = \sigma^2$$

$$\text{Cov}(e_i, e_{i'}) = \mathbb{E}[e_i e_{i'}^\top] = 0, \quad \forall i \neq i'$$

$$\text{VarCov}(\varepsilon) = \sigma^2 \mathbb{I} = \mathbb{E}[ee^\top]$$

$$\text{VarCov}(Y) = \text{VarCov}(\varepsilon) = \sigma^2 \mathbb{I}$$

$$\text{VarCov}(u) = \mathbb{E}[(u - Eu)(u - Eu)^\top]$$

$$\mathbb{I}_{n \times 1} \rightrightarrows \mathbb{I}_{1 \times n}$$

Ex: (Regression in narrow sense) $Y_i = \beta_0 + \beta_1 X_{i1} + \beta_2 X_{i2} + e_i$, $i=1, \dots, 50$.

Y_i : grade

X_{i1} : time spent on hw

X_{i2} : time spent on review

$$\begin{bmatrix} Y_1 \\ \vdots \\ Y_{50} \end{bmatrix} = \begin{bmatrix} 1 & X_{11} & X_{12} \\ \vdots & \vdots & \vdots \\ 1 & X_{50,1} & X_{50,2} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} e_1 \\ \vdots \\ e_{50} \end{bmatrix}$$

Ex: [Analysis of Variance (ANOVA)] $Y_{ij} = \mu + \alpha_i + \epsilon_{ij}$, $i=1,2,3$; $j=1,2$.

$$Y = \begin{bmatrix} Y_{11} \\ Y_{12} \\ \vdots \\ Y_{21} \\ Y_{22} \\ \vdots \\ Y_{31} \\ Y_{32} \end{bmatrix} \quad X = \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 \\ \hline 1 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 \\ \hline 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 1 \\ \hline \mu & \alpha_1 & \alpha_2 & \alpha_3 & \end{bmatrix} \quad \beta = \begin{bmatrix} \mu \\ \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix}$$

μ = "overall effect"
 α_i = "effect of i^{th} treatment"

$\hat{\theta}_1 = \overbrace{(\alpha_1 - \alpha_2)}^?$

$\hat{\theta}_2 = \overbrace{(\alpha_1 - (\alpha_2 + \alpha_3)/2)}$

rank(X) = 3

"Linear (in)dependent", "vector space", "basis", "column/row rank".

Linear Algebra Review

flayes 2.3.2 ; Scheffe App.I

Given $\{\underline{v}_1, \dots, \underline{v}_n\}$. $\alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n = \underline{0} \Rightarrow \begin{cases} \alpha_i = 0, \forall i : \text{"linearly independent"} \\ \text{not all } \alpha_i \text{ are } 0 \end{cases} \Rightarrow \begin{cases} \text{"linearly dependent"} \\ \text{"linearly dependent"} \end{cases}$

For "independent" case, may write

$$\underline{v}_1 = \beta_2 \underline{v}_2 + \dots + \beta_n \underline{v}_n$$

$$\text{Ex: } \underline{v}_1 = [1 \ 2 \ 1]^T \quad \underline{v}_2 = [1 \ 0 \ 1]^T$$

$$\alpha_1 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + \alpha_2 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \underline{0} \quad \begin{cases} \alpha_1 + \alpha_2 = 0 \\ 2\alpha_1 + 0 = 0 \\ \alpha_1 + \alpha_2 = 0 \end{cases} \Rightarrow \begin{cases} \alpha_1 = 0 \\ \alpha_2 = 0 \end{cases} \Rightarrow \text{"lin. indep."}$$

$$\text{Ex: } \underline{v}_1 = [1 \ 2 \ 1]^T \quad \underline{v}_4 = [-2 \ -4 \ -2]^T$$

$$\underline{v}_4 = -2 \cdot \underline{v}_1 \Rightarrow \text{"in dependent"}$$

$$\text{Ex: } \underline{v}_1, \underline{v}_2, \underline{v}_3 = [0 \ 1 \ 0]^T$$

$$\underline{v}_1 = \underline{v}_2 + 2\underline{v}_3 \Rightarrow \text{"lin dep."}$$

Def: Vector space: A set of all vectors that are lin. comb. of

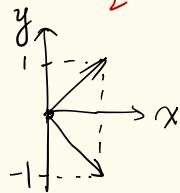
$$\{\underline{v}_i\}_{i=1}^n, \text{ i.e., } V = \left\{ \underline{v} = \sum_{i=1}^n \alpha_i \underline{v}_i, \alpha_i \in \mathbb{R} \right\}.$$

\underline{v}_i 's are said to span the vector space V , i.e., $V = \text{span}\{\underline{v}_1, \dots, \underline{v}_n\}$.

Ex: $V^{(1)} = \left\{ \alpha_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \alpha_i \in \mathbb{R} \right\}$



$$V^{(2)} = \left\{ r_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + r_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}, r_i \in \mathbb{R} \right\}$$



Def: A basis for V is a set of lin indep vectors that span V .

Ex: $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\} \quad \checkmark \quad \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \quad \checkmark \quad \cancel{\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}}$

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \quad \checkmark \quad \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\} \quad \times$$

Def: The dimension of vector space V is the # of vectors in any basis of V . Column/row rank: dim of (a) column/row vector space, respectively.

Ex: What's the rank of $V = \left\{ \begin{matrix} \tilde{v} = \alpha_1 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + \alpha_2 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + \alpha_3 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \alpha_i \in \mathbb{R} \right\}$?

Ans1: Basis = $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$ or

$\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$ or $\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$.

$$\text{rank}(V) = 2.$$

$$\begin{aligned} \text{Ans2: } V &= \left\{ \begin{matrix} \tilde{v} = \alpha_1 (\tilde{v}_2 + 2\tilde{v}_3) + \alpha_2 \tilde{v}_2 + \alpha_3 \tilde{v}_3 \\ = (\alpha_1 + \alpha_2) \tilde{v}_2 + (\alpha_2 + \alpha_3) \tilde{v}_3 \end{matrix} \right\}, \quad \tilde{v}_2 \perp \tilde{v}_3 \Rightarrow \text{rank}(V) = 2. \end{aligned}$$

3. Geometric interpretation of LS:

Problem Setup: $\hat{Y} = X\beta + \epsilon$, where $X \triangleq [\tilde{\xi}_1, \dots, \tilde{\xi}_p]$

Estimate β such that $J(\beta) = \| \hat{Y} - X\beta \|^2$ is minimized.

$$J(\beta) = \sum_{i=1}^n \left(Y_i - \sum_{j=1}^p x_{ij} \beta_j \right)^2$$

This is called "least-squares".

Claims: 1. $\hat{\beta}$ always exists, but
2. not always unique.

Goal Estimate β , σ^2 ; error (variance) of estimators,

e.g., $\text{Var}(\hat{\beta}_0)$, $\text{Var}(\hat{\beta}_1), \dots$; $\text{VarCov}(\hat{\beta}), \text{VarCov}(\hat{y})$.

Method 1: $\frac{\partial J}{\partial \beta_k} = \sum_{i=1}^n 2(Y_i - \sum_{j=1}^p x_{ij} \beta_j) \frac{\partial}{\partial \beta_k} \left(\dots + x_{ik} \beta_k + \dots \right)$

$$\boxed{J(\beta) = \sum_{i=1}^n (Y_i - \sum_{j=1}^p x_{ij} \beta_j)^2}$$

$$= \begin{cases} 0 & , k=1, \dots, p \\ \hat{\beta}_j = \hat{\beta}_j & \end{cases}$$

$-x_{ik}$

$$\Leftrightarrow \sum_i Y_i x_{ik} = \sum_i \sum_j x_{ij} \hat{\beta}_j x_{ik} \Leftrightarrow \boxed{X^T Y = X^T X \hat{\beta}} \quad \begin{matrix} \text{Normal} \\ \text{Equation} \\ (\text{NE}) \end{matrix}$$

where $X^T Y = \left[\sum_{i=1}^n x_{ik} Y_i \right]_{px1}$, $X^T X = \left[\sum_{i=1}^n x_{ij} x_{ik} \right]_{pxp}$, $\hat{\beta} = (X^T X)^{-1} X^T Y$

$$X^T X \hat{\beta} = \left[\sum_{j=1}^p \left(\sum_{i=1}^n x_{ij} x_{ik} \right) \hat{\beta}_j \right]_{px1}$$

$$\text{Method 2 : } \nabla_{\beta} J(\beta) = \begin{cases} 0 \\ \beta = \hat{\beta} \end{cases}$$

$$J(\beta) = \|Y - X\beta\|^2$$

$$\nabla_{\beta} J(\beta) = 2 \left[-X^T(Y - X\beta) \right] = \begin{cases} 0 \\ \beta = \hat{\beta} \end{cases}$$

$$X^T Y = X^T X \hat{\beta}$$

L.S. procedure: Find a vector in $\mathcal{L}(x)$ which is as close as possible to \tilde{Y} .

Claim: If $(\tilde{Y} - X\hat{\beta}) \perp \mathcal{L}(x)$, then $\hat{\beta}$ solves N.E.

Proof: $(\tilde{Y} - \hat{Y}) \perp \mathcal{L}(x)$

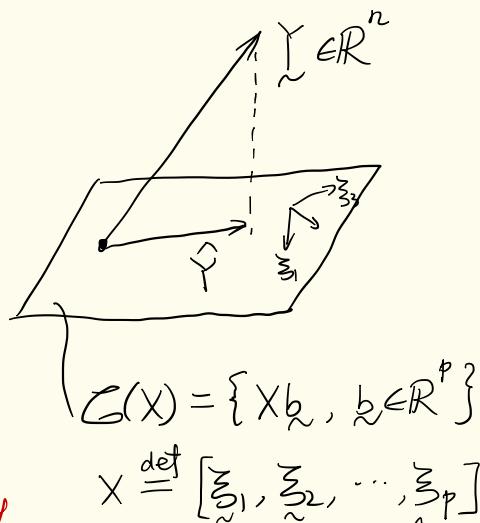
$$\Leftrightarrow (\tilde{Y} - \hat{Y}) \perp Xb, \forall b \in \mathbb{R}^p$$

$$\Leftrightarrow \Xi_j^T (\tilde{Y} - \hat{Y}) = 0, j=1, \dots, p$$

$$\Leftrightarrow [\Xi_1, \dots, \Xi_p]^T (\tilde{Y} - X\hat{\beta}) = 0$$

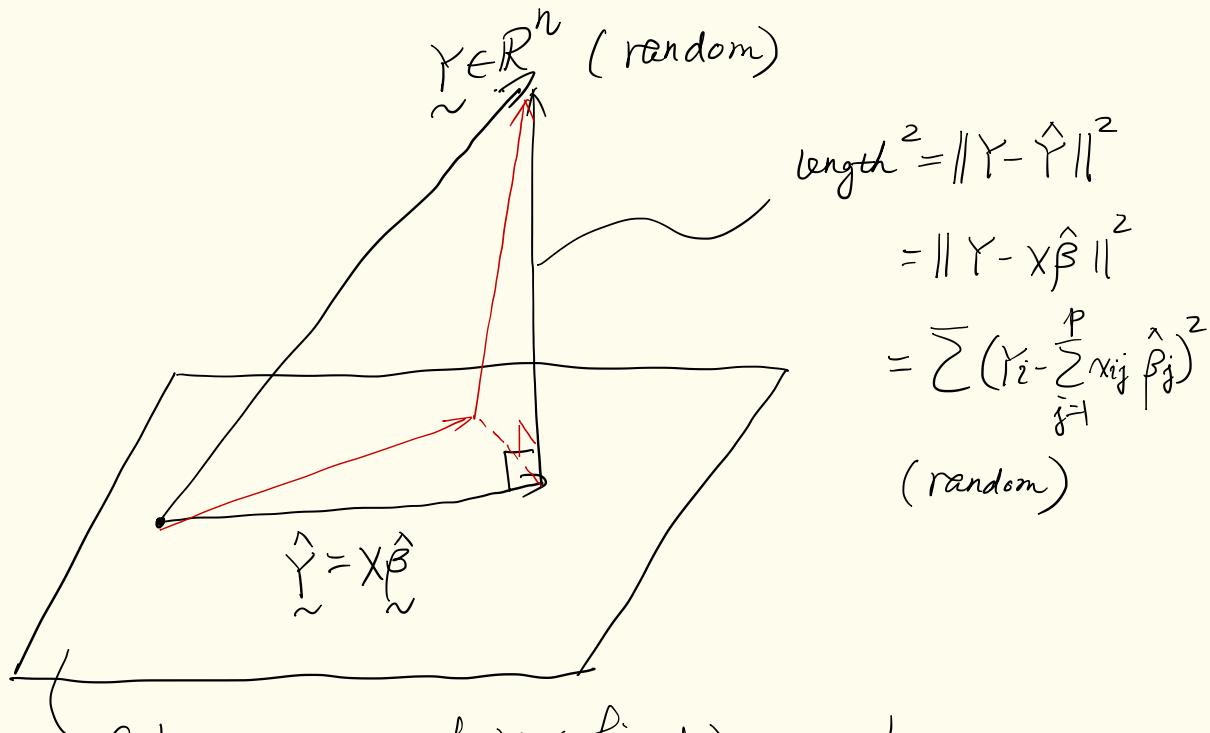
$$\Leftrightarrow X^T \tilde{Y} = X^T X \hat{\beta}$$

Regardless the rank of $X^T X$, there's a soln to the problem.



$$X \stackrel{\text{def}}{=} [\Xi_1, \Xi_2, \dots, \Xi_p]$$

$$\dim(\mathcal{L}(x)) = r \leq p$$



Column space of X (fixed), namely,

$$C(X) \subset \mathbb{R}^n$$

$$\det \left\| \begin{matrix} X \\ b \end{matrix}, b \in \mathbb{R}^p \right\}$$

If $\text{rank}(X) \triangleq r = p$ ① $\hat{\beta} = (X^T X)^{-1} X^T \tilde{Y}$ is unique soln.

$$\mathbb{E}[\hat{\beta}] = \mathbb{E}[(X^T X)^{-1} X^T \tilde{Y}] = (X^T X)^{-1} X^T X \beta = \beta \quad (\text{unbiased})$$

$$\begin{aligned} \text{VarCov}(\hat{\beta}) &= (X^T X)^{-1} X^T \underbrace{\text{VarCov}(Y)}_{\sigma^2 I} X (X^T X)^{-1} & \text{Note: } \text{Var}(\alpha X) = \alpha^2 \text{Var}(X) \\ &= \sigma^2 (X^T X)^{-1} & \text{VarCov}(\underbrace{\alpha^T w}_{\alpha^T \text{VarCov}(w) \alpha}) = \alpha^T \text{VarCov}(w) \alpha \end{aligned}$$

$$② \hat{Y} = X \hat{\beta} = X \underbrace{(X^T X)^{-1} X^T}_{H} Y = H Y$$

H : "hat" matrix, "orthogonal projector". $H^n = H$. Why?

$$\text{VarCov}(\hat{Y}) = H \text{Cov}(Y) H^T = \sigma^2 H H^T = \sigma^2 H^2 = \sigma^2 H = \sigma^2 \cdot X (X^T X)^{-1} X^T$$

$$Ex: \quad X = \begin{bmatrix} 2 & 1 \\ 1 & 2 \\ 1 & 1 \end{bmatrix} \quad Y = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad \boxed{Y = X\beta + e}$$

$$\hat{\beta} = (X^T X)^{-1} X^T Y = \left(\begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 2 \\ 1 & 1 \end{bmatrix} \right)^{-1} \left(\begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right)$$

$$= \begin{bmatrix} 6 & 5 \\ 5 & 6 \end{bmatrix}^{-1} \begin{bmatrix} 4 \\ 4 \end{bmatrix} = \begin{bmatrix} 6 & -5 \\ -5 & 6 \end{bmatrix} \cdot \frac{1}{11} \cdot \begin{bmatrix} 4 \\ 4 \end{bmatrix}$$

$$= \frac{4}{11} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

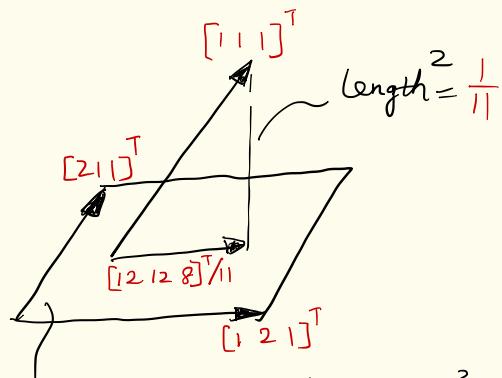
$$\text{VarCov}(\hat{\beta}) = \sigma^2 (X^T X)^{-1} = \frac{\sigma^2}{11} \begin{bmatrix} 6 & -5 \\ -5 & 6 \end{bmatrix}$$

$$H = X(X^T X)^{-1} X^T = \begin{bmatrix} 2 & 1 \\ 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 6 & -5 \\ -5 & 6 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \end{bmatrix} / 11 = \frac{1}{11} \begin{bmatrix} 10 & -1 & 3 \\ -1 & 10 & 3 \\ 3 & 3 & 2 \end{bmatrix}$$

$$\hat{Y} = H Y = \frac{1}{11} \begin{bmatrix} 12 \\ 12 \\ 8 \end{bmatrix} \neq Y$$

$$\text{LS err: } \|Y - \hat{Y}\|^2 = \frac{1}{11^2} \left\| \begin{bmatrix} 12-11 \\ 12-11 \\ 8-11 \end{bmatrix} \right\|^2 = \frac{1}{11^2} (1+1+9) = \frac{1}{11}$$

$$L(X) = \text{span} \left\{ \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right\} \subset \mathbb{R}^3$$



If $\text{rank}(X) \triangleq r < p$ (Not full column rank), what does $\hat{\beta}$ look like?

Ans: $r < p \Leftrightarrow X$ has a non-trivial null space.

$\Leftrightarrow \xi \in \mathbb{R}^p$ s.t. $X\xi = 0 = \sum_{i=1}^p c_i \underbrace{\xi_i}_{\sim}$. Then

$\exists \zeta \neq 0$

$$X\hat{\beta}_{\sim} = X\hat{\beta} + X\xi = X(\underbrace{\hat{\beta} + \xi}_{\tilde{\beta}})$$

$$\tilde{\beta} = \hat{\beta} + k\xi, k \in \mathbb{R} \text{ are all LS estimates.}$$

However, \hat{y} is unique: $\hat{y} = X(\hat{\beta} + k\xi) = X\hat{\beta} + k\underbrace{X\xi}_{0} = X\hat{\beta}$.

